

Dongho Kang

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RESEARCH INTERESTS

My research aims to create a legged robot that can perform natural, animal-like motion. Thus, my research interests are broad ranging to legged locomotion control, computational model of character animation and design optimization for robotics applications.

EDUCATION

ETH Zürich, Zurich, Switzerland

- Doctoral Student in Computer Science Apr 2020 – Present
 - Advisor: Prof. Dr. Stelian Coros
- M.Sc. ETH in Mechanical Engineering Sep 2016 – Aug 2019
 - Advisor: Prof. Dr. Marco Hutter
 - Graduated with distinction

Seoul National University, Seoul, South Korea

- B.Sc. in Mechanical Engineering and B.Sc. in Computer Science Mar 2009 – Aug 2016
 - Advisor: Prof. Dr. Dongjun Lee
 - Graduated with honor (Cum Laude)

RESEARCH EXPERIENCE

Computational Robotics Lab, ETH Zürich

- Scientific Assistant Dec 2019 – Present
 - Supervisors: Prof. Dr. Stelian Coros
 - Aim to build bio-inspired quadrupedal robots that perform more natural and animal-like motion.

Robotic Systems Lab, ETH Zürich

- Master's Student Sep 2017 – Nov 2019
 - Supervisors: David Höller, Dr. Jemin Hwangbo and Prof. Dr. Marco Hutter
 - Conducted the research on learning-based collision avoidance method for a legged robot ANYmal.
 - Participated in the development of RaiSim: a physics engine for robotics and AI research.

Interactive & Networked Robotics Lab, Seoul National University

- Undergraduate Research Assistant Sep 2014 – Jan 2016
 - Supervisors: Prof. Dr. Dongjun Lee
 - Participated in the research on state estimation and control strategy for multi-robot cooperative systems

PROFESSIONAL AFFILIATIONS & ACTIVITIES

NVIDIA, Zurich, Switzerland

- Deep Learning Intern Jun 2018 – Dec 2018
 - Projects: Super-Resolution and Anti-aliasing methods based on deep learning.

LeisureQ Inc., Seoul, South Korea

- Web Developer Intern Jan 2016 – Sep 2016
 - Projects: Backend web application for E-commerce website Gajago: <http://www.thegajago.com>

CNP Technology Inc., Seoul, South Korea

- Hardware and CAD Engineer Jan 2016 – Sep 2016

PUBLICATIONS

THESIS

- [1] Dongho Kang, “End-to-End Collision Avoidance from Depth Input with Memory-based Deep RL,” MSc thesis, the Department of Mechanical and Process Engineering, ETH Zürich, Aug 2019.

CONFERENCES

- [1] Dongho Kang, Simon Zimmermann, and Stelian Coros, “Animal Gaits on Quadrupedal Robots using Motion Matching and Model-Based Control,” in *International Conference on Intelligent Robots and Systems (IROS)*, Mar 2021 (accepted.)
- [2] Flavio De Vincenti, Dongho Kang, and Stelian Coros, “Control-Aware Design Optimization for Bio-Inspired Quadruped Robots,” in *International Conference on Intelligent Robots and Systems (IROS)*, Mar 2021 (accepted.)

- [3] Changu Kim, Hyunsoo Yang, Dongho Kang and Dongjun Lee, “2-D Cooperative Localization with Omni-Directional Mobile Robots,” in *International Conference on Ubiquitous Robots and Ambient Intelligence*, Goyang, South Korea, Oct 2015.

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| INVITED TALK | <ul style="list-style-type: none"> ▪ Robot Intelligence Lab, Korea University, Seoul, South Korea Apr 2021 ▪ NAVER LABS Corp., Seoul, South Korea Dec 2019 ▪ Max Planck ETH Center for Learning Systems Symposium, Tübingen, Germany Feb 2019 |
| AWARDS & SCHOLARSHIPS | <ul style="list-style-type: none"> ▪ Birkigt Scholarship, ETH Zürich Feb 2018 Stipendiary scholarship for international master student. ▪ Eminence Scholarship, Seoul National University Aug 2014 Full-tuition scholarship for one academic semester for outstanding academic performance. ▪ Merit-based Scholarship, Seoul National University Feb 2014 Half-tuition scholarship for one academic semester for outstanding academic performance. ▪ Development Fund Scholarship, Seoul National University Feb 2010 Full-tuition scholarship for one academic year for outstanding academic performance. |
| TEACHING EXPERIENCE | <p>ETH Zürich, Zurich, Switzerland</p> <ul style="list-style-type: none"> ▪ Teaching Assistant, Computational Models of Motion Feb 2021 – Jun 2021 ▪ Teaching Assistant, Visual Computing Sep 2020 – Dec 2020 <p>Seoul National University, Seoul, South Korea</p> <ul style="list-style-type: none"> ▪ Mentor, SNU Samsung Convergence Software Course Program Jan 2015 – Dec 2015 ▪ Teaching Assistant, MAE 446.204A: Dynamics Jan 2014 – Dec 2014 ▪ Teaching Assistant, PA 034.013: Basic Physics 2 Sep 2011 – Dec 2011 |
| LANGUAGES | <ul style="list-style-type: none"> ▪ Korean: Native language. ▪ English: Fluent (speaking, reading, writing). |
| TECHNICAL SKILLS | <p>Programming and Software C/C++, C#, Python, Matlab/Octave, Unix/Linux, Tensorflow, Pytorch, ROS, Open Dynamics Engine, Unity</p> <p>Experience with Robots Laikago, Aliengo, A1, ANYmal, GhostRobotics Vision60</p> |
| REFERENCES | <ul style="list-style-type: none"> ▪ Prof. Dr. Stelian Coros Assistant Professor in the Department of Computer Science ETH Zürich Stampfenbachstrasse 48 (Sumatrastrasse 11), 8092, Zurich, Switzerland scoros@inf.ethz.ch • +41 44 632 02 15 ▪ Prof. Dr. Marco Hutter Assistant Professor in the Department of Mechanical and Process Engineering ETH Zürich Leonhardstrasse 21, 8092 Zurich, Switzerland mahutter@ethz.ch • +41 44 632 74 17 ▪ Prof. Dr. Jemin Hwangbo Assistant Professor in the Department of Mechanical Engineering Korea Advanced Institute of Science and Technology jhwangbo@kaist.ac.kr ▪ Prof. Dr. Dongjun Lee Professor in the Department of Mechanical Engineering Seoul National University 1 Gwanak-Ro, Gwanak-Gu, Seoul, 08826, South Korea djlee@snu.ac.kr • +82 2 880 1724 |